IN THE CLAIMS

- device (1), in particular 1. (currently amended) Α transmitting a movement as well as corresponding forces and/or moments, comprising a drive $\frac{(2)}{}$ and a take-off $\frac{(3)}{}$, wherein the drive $\frac{(2)}{}$ and take-off $\frac{(3)}{}$ are coupled via at least one coupling element (4)—in such a manner that in the decoupled state a movement of the drive (2)—causes a movement of the coupling element -(4), wherein said movement is not suitable for transmitting a movement from the drive $\frac{(2)}{(2)}$ to the take-off-(3), and wherein in the decoupled state a movement of the drive (2)-causes a movement component of the coupling element (4) being essentially orthogonal thereto, and wherein a movement of the drive $\frac{(2)}{(2)}$ in the coupled state essentially causes a movement of the coupling elements (4)—in the same direction.
- device—(1), in particular 2. (currently amended) TheA for transmitting a movement as well as corresponding forces and/or moments, comprising a drive $\frac{(2)}{}$ and a take-off- $\frac{(3)}{}$, wherein the drive $\frac{(2)}{}$ and take-off $\frac{(3)}{}$ are coupled via at least one coupling element (4)—in such a manner that in the decoupled state a movement of the take-off (3)—causes a movement of the coupling elements -(4), wherein said movement is not suitable for transmitting a movement of the take-off (3) to the drive (2), and wherein in the decoupled state a movement of the take-off (3)—causes a movement components of the coupling elements (4)—being essentially orthogonal thereto, and wherein a movement of the take-off (3)—in the coupled state essentially causes a movement of the coupling elements (49-in the same direction.
- 3. (currently amended) The device according to claim 1 or 2, wherein the movement of the drive (2)—in the decoupled state cannot be transmitted to the take-off (3)—by the movement of the at least one coupling element (4)—because the mechanical

potential of the take-off (3)—formed by a storage device (14) cannot be overcome.

- 4. (currently amended) The device according to claim 1, 2 or 3, further comprising a coupling means (15)—which can cause a coupling as well as a decoupling of the drive (2)—and the take-off (3)—by means of the at least one coupling element (4).
- 5. (currently amended) The device according to claim 4, wherein in the decoupled state the coupling means (15)—is essentially not engaged with the at least one coupling element—(4).
- 6. (currently amended) The device according to claim 4 or 5, wherein in the coupled state the coupling means $\frac{(15)}{(15)}$ causes a limitation of the movability of the at least one coupling element $\frac{(4)}{(15)}$.
- 7. (currently amended) The device according to—any one—of claims 4—to—6, wherein the coupling means (15)—comprises at least one coupling locking device or coupling locking element (17)—for limiting the movability of the at least one coupling element (4)—in the coupled state.
- 8. (currently amended) The device according to claim 7, wherein a mechanical potential formed by a storage device—(14), has to be overcome for moving the coupling locking element—(17) from the decoupled state in a coupled state and/or from the coupled state in the decoupled state.
- 9. (currently amended) The device according to claim 7—or 8, wherein the cooperation between coupling locking elements (17)—and coupling element(s) (4)—is such that the forces applied by the at least one coupling element (4)—cause a movement tendency towards a stronger and more reliable engagement, so that at the beginning of the force application

there is only a partial engagement but then an essentially reliable position is reached.

- 10. (currently amended) The device according to claim 7, 8 or 9, wherein the coupling means (15)—further comprises an actuator (16)—for positioning the coupling locking element—(17).
- 11. (currently amended) The device according to claim 10, wherein the actuator (16)—is suitable for causing a displacement of the coupling locking element (17)—via a mechanical potential formed by a storage device—(14), into a position being suitable for coupling.
- 12. (currently amended) The device according to any one of claims 9, 10 or 11, wherein the actuator is bistable.
- 13. (currently amended) The device according to claim 10_{7} —11—or 12_{7} , wherein the actuator (16)—comprises an electromagnet arrangement having at least one yoke (26)—and a coil—(27).
- 14. (currently amended) The device according to any one of the preceding claims l, wherein the coupling device is configured manipulation resistant such that the movement directions of the coupling means (15)—are essentially orthogonal with respect to the attacks to be expected in the longitudinal direction of the device and/or counter-moments compensate for the forces caused by the attack.
- 15. (currently amended) The device according to any one of the preceding claims 1, wherein a mechanical potential formed by a storage device—(9), has to be overcome for a relative movement between the drive (2)—and take-off—(3), wherein said potential is lower than a mechanical potential of the take-off (3)—formed by a storage device—(14).

- 16. (currently amended) The device according to any one of claims 7—to 15, wherein the potential formed by a storage device—(9), leads to the fact that when the force at the drive (2)—falls below a specific value, at least one coupling locking element (17)—can essentially be brought into and/or out of a coupling position without the application of a force.
- 17. (currently amended) The device according to any one of the preceding claims 1, wherein the drive (2)—and take-off (3)—are coupled via the at least one coupling element (4)—in such a manner that in the decoupled state a movement of the take-off—(3), with a stationary drive—(2), causes a movement component of the at least one coupling element (4)—being orthogonal thereto, and that a movement of the take-off (3) in the coupled state essentially causes a movement of the at least one coupling element (4)—in the same direction.
- 18. (currently amended) The device according to any one of the preceding claims claim 1, wherein a movement of the at least one coupling element (4)—being essentially orthogonal with respect to the movement direction of the drive essentially does not cause a movement of the take-off—(3).
- 19. (currently amended) The device according to any one of the preceding claims claim 1, wherein a rotational movement of the at least one coupling element (4)—essentially causes a rotational movement of the take-off—(3).
- 20. (currently amended) The device according to any one of the preceding claims 1, wherein the at least one coupling element (4)—communicates with the drive (2)—via at least one first guide means (5, 7).
- 21. (currently amended) The device according to claim 20, wherein the at least one first guide means (5, -7)—comprises

at least one first slide surface $\frac{(5)}{}$ for a contact with at least one first slide element $\frac{(7)}{}$.

- 22. (currently amended) The device according to claim 20-or 21, wherein the at least one first slide surface (5)—is inclined with respect to an axial movement direction of the coupling element—(4).
- 23. (currently amended) The device according to claim 21—or 22, wherein upon a rotation of the drive—(2), the at least one first slide element (7)—being arranged at the drive (2) essentially moves on a plane being essentially perpendicular with respect to an axial movement direction of the at least one coupling element—(4), wherein it contacts and/or moves along at least one first slide surface—(5).
- 24. (currently amended) The device according to any one of the preceding claims claim 1, wherein the at least one coupling element (4)—comprises at least one second guide means (6, 8) communicating with the take-off—(3).
- 25. (currently amended) The device according to claim 24, wherein the at least one second guide means comprises at least one second slide surface (6)—for a contact with at least one second slide element—(8).
- 26. (currently amended) The device according to claim 25, wherein the at least one second slide surface (6)—is essentially parallel with respect to an axial movement direction of the at least one coupling element—(4).
- 27. (currently amended) The device according to claim 25 or 26, wherein upon a rotation of the at least one coupling element (4), the second slide element (8) being arranged at the take-off (3)—essentially moves on a plane being essentially perpendicular with respect to an axial movement direction of

the at least one coupling element—(4), wherein it contacts and/or moves along at least one second slide surface—(6).

- 28. (currently amended) The device according to any one of the preceding claims 1, wherein the take-off (3)—for generating a mechanical potential formed by a storage device (14) communicates with at least one third guide means—(10, 11).
- 29. (currently amended) The device according to claim 28, comprising at least one third guide means and at least one third slide surface (10)—for a contact with at least one third slide element (11)—being arranged in a guide—(12).
- 30. (currently amended) The device according to claim 29, wherein the at least one third slide surface (10)—is inclined with respect to a rotational axis of the take-off—(3).
- 31. (currently amended) The device according to claim 29 or 30, wherein upon a rotation of the take-off—(3), the at least one third slide element (11)—being arranged in a guide (12) essentially moves along the rotational axis of the take-off (3).
- 32. (currently amended) The device according to any one of claims 29—to 31, wherein the at least one third slide element (11)—is pre-stressed with respect to the at least one third slide surface—(10).
- 33. (currently amended) The device according to any one of the preceding claims 1, wherein the coupling element (4)—is pre-stressed with respect to the take-off (3)—and/or with respect to the drive—(2).
- 34. (currently amended) The device according to $\frac{\text{any one of}}{\text{claims } 1 \text{to } -33}$, wherein the mechanical potential formed by a

storage device—(14, 21), which has to be overcome for the movement of the take-off, essentially acts on the coupling element—(4).

- 35. (currently amended) The device according to any one of claims 1—to 34, wherein the coupling element (4)—can be prestressed by a spring element—(21), which preferably comprises a torsion spring and/or a potential arrangement and wherein the coupling element (4)—can preferably be limited in its angle of rotation.
- 36. (currently amended) The device according to claim 35, wherein the limiting of the angle of rotation is achieved by the co-operation of the take-off $\frac{3}{3}$ and a stop- $\frac{22}{3}$.
- 37. (currently amended) The device according to any one of claims 1—to 14, 16 to 19 or 33, wherein the coupling element (4)—consists of at least one roller element (23)—or sliding element.
- 38. (currently amended) The device according to claim 37, wherein the roller element (23)—or the sliding element is guided in the drive (2)—in such a manner that it can essentially move in radial direction with respect to said drive.
- 39. (currently amended) The device according to claim 37—or—38, wherein the roller element (23)—or the sliding element is pressed outwards by a spring element (24)—preferably consisting of a leg spring.
- 40. (currently amended) The device according to claim 37, 38 or 39, wherein the take-off (3)—is configured such that it comprises at least one projection (25)—at its inner side on which the roller element (23)—or sliding element moves.

- 41. (currently amended) The device according to any one of claims 37—to 40, wherein the roller element (23)—or slide element can give way in case of a relative movement between the drive (2)—and take-off (3)—when the drive (2)—and take-off (3)—are not coupled with each other.
- 42. (currently amended) The device according to any one of claims 38—to 40, wherein the drive (2)—and the take-off (3) are configured such that the roller element (23)—or sliding element can move inwards in case of a rotation of the drive (2)—in that it overcomes the potential of the spring element (24)—wherein the torque generated thereby is not sufficient to overcome a mechanical potential at the take-off—(3), which is formed by a storage device.
- 43. (currently amended) The device according to any one of claims 37—to 42, wherein a coupling locking element (17)—can be positioned between the coupling elements (4)—in such a manner that said coupling elements cannot give way and thus the drive (2)—and take-off (3)—are coupled with each other.
- 44. (currently amended) The device according to claim 43, wherein the coupling locking element (17)—is supported in such a manner that the movement being necessary for the engagement is essentially perpendicular to the attack direction.
- 45. (currently amended) The device according to claim 43 or 44, wherein the mass center of the coupling locking element (17) is selected such that, when the drive (2) and take-off (3) are not coupled with each other, it is essentially supported with regard to its rotational axis that an engagement of the drive (2) and take-off (3) cannot occur in case of accelerations in the attack direction.

- 46. (currently amended) The device according to any one of claims 37—to 45, wherein the coupling locking element (17)—is connected to a switch element (30)—via a coupling locking spring—(18).
- 47. (currently amended) The device according to claim 46, wherein the switch element (30)—is operated via the actuator (16) which comprises an electromagnet arrangement (26, 27).
- 48. (currently amended) The device according to claim 46 or 47, wherein the coupling locking spring (18)—is arranged and configured such that when the switch element (30)—is operated by the electromagnet arrangement of the actuator—(16), the coupling locking element (17)—can be moved into a position by the coupling locking spring (18)—in which the drive (2)—and take-off (3)—are coupled with each other.
- 49. (currently amended) The device according to claim 46, 47 or 48, wherein the switch element (30)—and/or the coupling locking element (17)—comprises a switch element spring—(31).
- 50. (currently amended) The device according to claim 49, wherein, for coupling, the switch element (30)—can be moved via the actuator (16)—such that the switch element spring (31)—is pre-stressed and that the coupling locking element (17)—connected to the switch element (30)—can be moved into a coupled position by the spring forces.
- 51. (currently amended) The device according to claim 50, wherein the movement of the coupling locking element (17) into a coupled position is preferably limited by a stop (33) so that the coupling locking spring (18) can be pre-stressed.
- 52. (currently amended) The device according to claim 50-or -51, wherein the pre-stress of the switch element spring (31)—is suitable to move the coupling locking element (17)—into a

decoupled position, when a magnetic force of the actuator $\frac{(16)}{(16)}$ is removed from the switch element $\frac{(30)}{(30)}$ for a short period of time.

- 53. (currently amended) The device according to claim 50, 51 or 52, wherein the pre-stress of the coupling locking element (18)—and/or the switch element spring (31)—is suitable to release the switch element (30)—from the electromagnet arrangement of the actuator (16)—for decoupling, when a magnetic force of the actuator (16)—is removed from the switch element, especially also when the coupling locking element (17)—is still clamped between the coupling elements (4)—due to an external torque acting on the drive.
- 54. (currently amended) The device according to any one of claims 37 to 45, wherein the coupling locking element (17) and the switch element (30)—are configured separately from each other and each comprises a spring element (18, 31).
- 55. (currently amended) The device according to claim 54, wherein the switch element (30)—is operated via the actuator (16)—which comprises an electromagnet arrangement (26, 27).
- 56. (currently amended) The device according to claim 54—or 55, wherein the spring elements (18, 31)—are arranged such that the switch element (30)—holds the coupling locking element (17)—in a decoupled position and releases the coupling locking element (17)—when it is operated by the actuator (16), so that said coupling locking element can assume a coupled position.
- 57. (currently amended) The device according to claim 54, 55 or 56, wherein the coupling locking element (17)—is connected to the coupling locking spring (18)—and the switch element (30)—is connected to the switch element spring—(31).

- 58. (currently amended) The device according to claim 57, wherein the coupling locking element (17)—is held in a decoupled condition by the switch element (30)—via its switch element spring—(31), wherein the switch element spring—(31) is pre-stressed.
- 59. (currently amended) The device according to claim 58, wherein the pre-stress of the switch element spring (31)—is suitable to release the switch element $\frac{(30)}{}$ from the $\frac{(16)}{}$ for electromagnet arrangement of actuator decoupling, when a magnetic force of the actuator (16)—is removed from the switch element—(30), especially also when the coupling locking element (17)—is still clamped between the coupling elements (4)—due to an external torque acting on the drive.
- 60. (currently amended) The device according to any one of claims 37—to 59, wherein the actuator (16)—comprises an electromagnet consisting of at least one yoke (26)—and a coil (27), wherein the effective direction of the magnetic field between the switch element (30)—and the yoke (26)—is essentially perpendicular with respect to the attack direction.
- 61. (currently amended) The device according to claim 60, wherein a current is lead through the coil (27)—for coupling the drive (2)—and the take-off—(3), said current effecting a magnetic flux through the yoke (26)—and the coupling locking element (17)—and/or the switch element—(30), which are preferably at least partially magnetically permeable, wherein the coupling locking element (17)—is moved such that the roller element—(23) or sliding element can transmit a torque onto the take-off—(3).

- 62. (currently amended) The device according to any—one of claims 9—to 61, wherein the actuator (16)—can be operated via a transponder.
- 63. (currently amended) A method, in particular for transmitting a movement as well as corresponding forces and/or moments by means of a coupling, thereby using a device according to any one of claims 1 to 62.
- 64. (currently amended) A lock device comprising a device according to any one of claims 1-to-62.
- 65. (original) The lock device according to claim 64, wherein the lock device can be operated electrically and/or electromagnetically.
- 66. (currently amended) The lock device according to claim 64—or 65, wherein the actuator and/or the device can be operated via a transponder.